# Data Mining Examination ANSWERS 

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1. (i). The SVD is the factorization $A=U S V^{T}$, where $U \in O(m), V \in O(n)$ and $S \in$ $\mathbb{R}^{m \times n}$ is a diagonal matrix whose diagonal elements satisfy

$$
s_{1} \geq s_{2} \geq \cdots \geq s_{n}
$$

The diagonal elements of $S$ are called the singular values of $A$.

## 5 pts

(ii). Given any pair of matrices $A, B \in \mathbb{R}^{m \times n}$, their Frobenius inner product is given by

$$
\langle A, B\rangle_{F}=\sum_{i=1}^{m} \sum_{j=1}^{n} A_{i j} B_{i j} .
$$

The Frobenius norm is defined by

$$
\|A\|_{F}=\sqrt{\langle A, A\rangle_{F}}
$$

4 pts
(iii). If $A=\left(\begin{array}{llll}\mathbf{a}_{1} & \mathbf{a}_{2} & \cdots & \mathbf{a}_{n}\end{array}\right)$, then

$$
\|Q A\|_{F}^{2}=\sum_{k=1}^{n}\left\|Q \mathbf{a}_{k}\right\|_{2}^{2}=\sum_{k=1}^{n}\left\|\mathbf{a}_{k}\right\|_{2}^{2}=\|A\|_{F}^{2}
$$

because an orthogonal matrix leaves the Euclidean norm of a vector unchanged.
Now

$$
\|A R\|_{F}=\left\|(A R)^{T}\right\|_{F}=\left\|R^{T} A^{T}\right\|_{F}=\left\|A^{T}\right\|_{F}=\|A\|_{F}
$$

because $R \in O(n)$ if and only if $R^{T} \in O(n)$, and the Frobenius norm is invariant under the transpose operation, which is obvious from its definition.

## 4 pts

(iv). We have

$$
\|A-Q\|_{F}^{2}=\left\|U S V^{T}-Q\right\|_{F}^{2}=\left\|U^{T}\left(U S V^{T}-Q\right) V\right\|_{F}^{2}=\left\|S-U^{T} Q V\right\|_{F}^{2}
$$

since the Frobenius norm is invariant under pre- and post-multiplication by orthogonal matrices. Thus

$$
\|A-Q\|_{F}^{2}=\|S-W\|^{2}=\langle S-W, S-W\rangle_{F}=\|S\|_{F}^{2}-2\langle S, W\rangle_{F}+\|W\|_{F}^{2}
$$

Now every column of an orthogonal matrix is a unit vector, which implies $\|W\|_{F}^{2}=$ $n$. Further, since $S$ is a diagonal matrix, $\langle S, W\rangle_{F}=s_{1} W_{11}+\cdots+s_{n} W_{n n}$. Therefore

$$
\|A-Q\|_{F}^{2}=\|S\|_{F}^{2}-2 \sum_{k=1}^{n} s_{k} W_{k k}+n=\sum_{k=1}^{n} s_{k}^{2}-2 s_{k} W_{k k}+1
$$

(v). We have

$$
\|A-Q\|_{F}^{2}=\sum_{k=1}^{n} s_{k}^{2}+1-2 \sum_{k=1}^{n} s_{k} W_{k k}
$$

Thus minimizing $\|A-Q\|_{F}$ is equivalent to maximizing $\sum_{k=1}^{n} s_{k} W_{k k}$, for $W \in O(n)$. Now every column of an orthogonal matrix is a unit vector, so its diagonal elements satisfy $-1 \leq W_{k k} \leq 1$. Hence

$$
\sum_{k=1}^{n} s_{k} W_{k k} \leq \sum_{k=1}^{n} s_{k}
$$

with equality if $U^{T} Q V=W=I$, or $Q=U V^{T}$.
The Procrustes problems arises in many areas, but one possible application is in missile guidance systems, where $A$ is a perturbed orthogonal matrix, generated by hardware, which specifies the orientation of the missile.

5 pts

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2. (i). Let $\mathbf{x}_{1}, \ldots, \mathbf{x}_{n}$ be points in $\mathbb{R}^{d}$. The $k$-means algorithm is a simple method for iteratively updating a set of $k$ cluster centres $\mathbf{m}_{1}, \ldots, \mathbf{m}_{k}$. At the start of the algorithm, these points can be any vectors.
Now the $k$ cluster centres partition $\mathbb{R}^{d}$ into $k$ clusters: we let the $i$ th cluster $C_{i}$ be those points in $\mathbb{R}^{d}$ for which $\mathbf{m}_{i}$ is the closest cluster centre, that is

$$
C_{i}=\left\{\mathbf{x} \in \mathbb{R}^{d}:\left\|\mathbf{x}-\mathbf{m}_{i}\right\|=\min _{1 \leq \ell \leq k}\left\|\mathbf{x}-\mathbf{m}_{\ell}\right\|\right\}, \quad 1 \leq i \leq n
$$

and students are not expected to deal with ambiguous cases for which some points lie in more than one cluster. We then replace each cluster centre $\mathbf{m}_{i}$ by the centroid of the subset of points in $\mathbf{x}_{1}, \ldots, \mathbf{x}_{n}$ which are contained in the $i$ th-cluster (the centroid of a finite set of points $\mathbf{v}_{1}, \ldots, \mathbf{v}_{j}$ is simply the sample average $\left.\left(\mathbf{v}_{1}+\cdots+\mathbf{v}_{j}\right) / j\right)$. The new cluster centres then define corresponding new centres, and we then repeat the procedure until the cluster centres converge.

## 8 pts

(ii). We can summarize the links between websites by a single matrix containing 0 s and 1s. Specifically, if there are $N$ websites, then we let $W_{i j}=1$ if site $i$ links to site $j$ and $i \neq j$, but otherwise set $W_{i j}=0$. A
Page and Brin decided to rank these $N$ websites by simulating user behaviour with a Markov model based on the connectivity matrix $W$. Specifically, we imagine vast numbers of users surfing the web in discrete time. At the $k$ th step, the vector $\pi^{(k)}$ denotes the probability distribution for our users, that is, $\pi_{i}^{(k)}$ is the probability that a user is surfing site $i$ at time $k$. We then let our users surf to new sites according to the transition matrix $P \in \mathbb{R}^{N \times N}$, where

$$
\begin{equation*}
P_{i j}=\frac{W_{i j}}{\sum_{k=1}^{N} W_{i k}}, \quad 1 \leq i, j \leq N \tag{1}
\end{equation*}
$$

Further, we shall assume that $\sum_{k=1}^{n} W_{i k} \neq 0$, for all $i$, to avoid a zero denominator in the definition of $P$ (we are assuming that there are no dangling pages, to use Google's jargon).
Thus the new probability vector is given by

$$
\begin{equation*}
\pi^{(k+1)}=P^{T} \pi^{(k)} \tag{2}
\end{equation*}
$$

and, over time, we hope to obtain an invariant measure (or stationary probability vector) $\pi$. Unfortunately this Markov chain turns out to be inadequate, because most sites tend to fall into isolated clusters and it inherits this stagnation. One way to avoid this is a teleporting random walk: we choose a parameter $c \in(0,1)$ and either use $P$ with probability $c$, or move to one of the $N$ websites with equal probability. Thus our new transition matrix is

$$
\begin{equation*}
M=c P+(1-c) \frac{\mathbf{e e}^{T}}{N}, \tag{3}
\end{equation*}
$$

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where

$$
\mathbf{e}=\left(\begin{array}{c}
1  \tag{4}\\
1 \\
\vdots \\
1
\end{array}\right)
$$

The new invariant measure vector $\pi$ now satisfies $M^{T} \pi=\pi$.
Page and Brin decided to define the rank vector $\mathbf{r}=N \pi$. Thus the last equation becomes

$$
\begin{equation*}
\left(I-c P^{T}\right) \mathbf{r}=(1-c) \mathbf{e} \tag{5}
\end{equation*}
$$

This linear system contains $N$ linear equations in $N$ unknowns, but $N \approx 10^{9}$. Unfortunately, direct elimination requires $T(N)=C N^{3}$ seconds, where $T\left(10^{3}\right) \approx 1$ on basic modern computer. Hence elimination is completely unsuitable. Fortunately, a simple iterative algorithm called Jacobi's method is available. Specifically, given any $n \times n$ matrix $A$, Jacobi's method attempts to solve $A \mathbf{x}=\mathbf{y}$ as follows. We first choose any initial vector $\mathbf{x}^{(0)}$. Then, given $\mathbf{x}^{(k-1)}$, we define $\mathbf{x}^{(k)}$ by the equation

$$
\begin{equation*}
x_{i}^{(k)}=\frac{y_{i}}{A_{i i}}-\sum_{j=1, j \neq i}^{n}\left(\frac{A_{i j}}{A_{i i}}\right) x_{j}^{(k)}, \quad 1 \leq i \leq n \tag{6}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\mathbf{r}^{(k)}=c P^{T} \mathbf{r}^{(k-1)}+(1-c) \mathbf{e} . \tag{7}
\end{equation*}
$$

12 pts
3. (i). We have $d s=r^{2} d t$, so that

$$
\begin{aligned}
\Gamma(\alpha) & =\int_{0}^{\infty} e^{-r^{2} t} r^{-2+2 \alpha} t^{-1+\alpha} r^{2} d t \\
& =r^{2 \alpha} \int_{0}^{\infty} e^{-r^{2} t} t^{-1+\alpha} d t
\end{aligned}
$$

and the formula now follows.
5 pts
(ii). If we set $r^{2}=\|\mathbf{x}\|_{2}^{2}+c^{2}$, then we obtain

$$
\begin{aligned}
\frac{1}{\left(\|\mathbf{x}\|_{2}^{2}+c^{2}\right)^{\alpha}} & =\frac{1}{\Gamma(\alpha)} \int_{0}^{\infty} e^{-\left(\|\mathbf{x}\|_{2}^{2}+c^{2}\right) t} t^{-1+\alpha} d t \\
& =\frac{1}{\Gamma(\alpha)} \int_{0}^{\infty} e^{-\|\mathbf{x}\|_{2}^{2} t} e^{-c^{2} t} t^{-1+\alpha} d t
\end{aligned}
$$

5 pts
(iii). Let $A \in \mathbb{R}^{n \times n}$ be the interpolation matrix whose elements are given by

$$
A_{j k}=\frac{1}{\left(\left\|\mathbf{x}_{j}-\mathbf{x}_{k}\right\|_{2}^{2}+c^{2}\right)^{\alpha}}, \quad 1 \leq j, k \leq n
$$

Then

$$
\begin{aligned}
\mathbf{a}^{T} A \mathbf{a} & =\sum_{j=1}^{n} \sum_{k=1}^{n} a_{j} a_{k} A_{j k} \\
& =\frac{1}{\Gamma(\alpha)} \int_{0}^{\infty}\left(\sum_{j=1}^{n} \sum_{k=1}^{n} a_{j} a_{k} e^{-\left\|\mathbf{x}_{j}-\mathbf{x}_{k}\right\|_{2}^{2} t}\right) e^{-c^{2} t} t^{-1+\alpha} d t
\end{aligned}
$$

Now the double sum in the integrand is non-negative for all $t>0$, and can be zero only if $\mathbf{a}=0$. Since the remainder of the integrand is positive for $t>0$, we deduce that $A$ is a symmetric positive definite matrix. Hence it is invertible, and we can interpolate with this radial basis function.
4. (i). We have, recalling that $S_{p q}=s_{p} \delta_{p q}$,

$$
\begin{aligned}
A_{i j} & =\sum_{p=1}^{m} U_{i p}\left(S V^{T}\right)_{p j} \\
& =\sum_{p=1}^{m} \sum_{q=1}^{n} U_{i p} S_{p q} V_{j q} \\
& =\sum_{p=1}^{n} s_{p} U_{i p} V_{j p} \\
& =\sum_{p=1}^{n} s_{p} \mathbf{u}_{p}(i) \mathbf{v}_{p}(j) \\
& =\left(\sum_{p=1}^{n} s_{p} \mathbf{u}_{p} \mathbf{v}_{p}^{T}\right)_{i j}
\end{aligned}
$$

as required.
6 pts
(ii). We have

$$
A \mathbf{v}_{\ell}=\sum_{k=1}^{r} s_{k} \mathbf{u}_{k} \mathbf{v}_{k}^{T} \mathbf{v}_{\ell}=0
$$

if $\ell>r$.
3 pts
(iii). We have

$$
A \mathbf{x}=\sum_{k=1}^{r} s_{k}\left(\mathbf{v}_{k}^{T} \mathbf{x}\right) \mathbf{u}_{k}
$$

(iv). The orthogonal invariance of the Frobenius norm implies

$$
\left\|A-A_{r}\right\|_{F}^{2}=\left\|S-S_{r}\right\|_{F}^{2}=s_{r+1}^{2}+\cdots+s_{n}^{2}
$$

where $S_{r}=\operatorname{diag}\left\{s_{1}, \ldots, s_{r}, 0, \ldots, 0\right\}$.
3 pts
(v). We have $\left\|\left(A-A_{r}\right) \mathbf{x}\right\|_{2}=\left\|\left(S-S_{r}\right) \mathbf{y}\right\|_{2}$, where $\mathbf{y}=V^{T} \mathbf{x}$ and $\|\mathbf{y}\|_{2}=\|\mathbf{x}\|_{2}$. Now

$$
\left\|\left(S-S_{r}\right) \mathbf{y}\right\|_{2}^{2}=s_{r+1}^{2} y_{r+1}^{2}+\cdots+s_{n} y_{n}^{2} \leq s_{r+1}^{2}\|\mathbf{y}\|^{2}
$$

because $s_{1} \geq \cdots \geq s_{n}$. Hence $\left\|\left(A-A_{r}\right) \mathbf{x}\right\|_{2} \leq s_{r+1}\|\mathbf{x}\|_{2}$, as required.

